

1. A device for clamping and ablating cardiac tissue comprising:

Sub A2

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1. The first step is to identify the key components of the system. This involves understanding the hardware and software involved, as well as the data flow and the roles of the various components.

2. The second step is to define the system's architecture. This involves determining the overall structure of the system, including the main components and their interactions.

3. The third step is to design the system's components. This involves creating detailed specifications for each component, including its functions, inputs, and outputs.

4. The fourth step is to implement the system. This involves building the system according to the design specifications, using appropriate programming languages and tools.

5. The fifth step is to test the system. This involves verifying that the system meets the requirements and that it operates correctly under various conditions.

6. The sixth step is to deploy the system. This involves installing the system on the target hardware and making it available to the users.

7. The seventh step is to maintain the system. This involves monitoring the system's performance, updating it as needed, and troubleshooting any issues that arise.

8. The eighth step is to evaluate the system. This involves assessing the system's effectiveness, efficiency, and user satisfaction, and using this information to improve the system.

9. The ninth step is to document the system. This involves creating a comprehensive set of documentation, including user manuals, technical specifications, and test reports.

10. The tenth step is to archive the system. This involves storing the system's data and documentation in a secure and accessible location for future reference.

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SUB E1

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4. The apparatus of claim 3 wherein the parallel grasping jaws spaced apart between approximately 1 to 15 mm when in the closed position.

